



# MAZAK INTEGREX 40 – ATC | 1989 | MAZATROL

### **TURN MILL**



**MODEL** 

**INTEGREX 40 - ATC** 

**YEAR** 

1989

**CONTROLLER** 

**MAZATROL** 





#### **TECHNICAL DATA**

Maximum swing mm	· Items	Chucker	Universal		
Maximum cutting diameter mm			1000	1500	2000
Distance between centers mm					
Turret travel:	Maximum cutting diameter mm				
X axis   615 (605 + 10)     Z axis mm		·-	1040	1550	2060
Taxis mm					
Spindle nose		712.00			#
Hole through spindle		1102			2122
Spindle internal taper  Spindle center  Spindle speed & range  No. of spindle speed changes (Hydraulic shift: 3 steps) 5 3000 rpm (3 - 2200 rpm)  Tailstock spindle travel mm  Tailstock spindle center  M.T. No. 5  Maximum tailstock thrust force  Maximum load  Chuck work: 300 kg (400 kg) Shaft work: 1500 kg including chuck KITAGAWA N-12A0815  Rapid speed: X axis Z axis Least command increment: X axis mm Z axis Least command increment: X axis mm Z axis Mindrive motor AC motor  Net weight: kg  9100  9400  10300  11100					V 2
Spindle center	Chindle integral target	Ac			
No. of spindle speed changes		AS			
Chydraulic shift: 3 steps   5		No			P.
Tailstock spindle travel mm	Springre speed a range	MO.	or spinare	speed chang	es
Tailstock spindle travel mm		, Eny	2000 200	TTL: 3 Steps	21
Tailstock spindle center  Maximum tailstock thrust force  Maximum load  Chuck work: 300 kg (400 kg)  Shaft work: 1500 kg  including chuck  Standard chuck  Rapid speed:  X axis  Z axis  Least command increment:  X axis mm  Z axis  O.001 (in diameter)  Z axis  Main drive motor  Net weight: kg  9100  9400  10300  11100	Tailstock spindle travel mm	9 3	3000 rpm	130 - 2200 FF	ALD A
Maximum tailstock thrust force         -         1500 kg           Maximum load         Chuck work: 300 kg (400 kg)           Shaft work: 1500 kg         including chuck           Standard chuck         KITAGAWA N-12A0815           Rapid speed:         12,000 mm/min           X axis         15,000 mm/min           Least command increment:         0.001 (in diameter)           X axis mm         0.001           Z axis         0.001           Main drive motor         AC motor           Net weight: kg         9100         9400         10300         11100		35	MT		
Maximum load         Chuck work: 300 kg (400 kg)           Standard chuck         1500 kg           Rapid speed:         KITAGAWA N-12A0815           X axis         12,000 mm/min           Z axis         15,000 mm/min           Least command increment:         0.001 (in diameter)           X axis mm         0.001           Z axis         0.001           Main drive motor         AC motor           Net weight: kg         9100         9400         10300         11100			1921-		
Shaft work: 1500 kg   including chuck		A STATE OF THE PARTY OF THE PAR	rk. 300 h		
Standard chuck	* Tax Illiam Your	Shaft work: 1500 kg (400 kg)			
Standard chuck         KITAGAWA N-12A0815           Rapid speed:         12,000 mm/min           X axis         15,000 mm/min           Least command increment:         0.001 (in diameter)           X axis mm         0.001           Z axis         0.001           Main drive motor         AC motor           Net weight: kg         9100         9400         10300         11100		Sud i c No			
Rapid speed:	Standard chuck		KITAGAWA	N_12AOQ1E	
X axis			KITHOMMA	H-IEAUOIS	
Z axis			12 000	mm/min	
Least command increment:       X axis mm       0.001 (in diameter)         Z axis       0.001         Main drive motor       AC motor       40HP (30KW)         Net weight:       kg       9100       9400       10300       11100		Contract of the Contract of th			
X axis mm			20,000	Many and to	
Z axis 0.001  Main drive motor AC motor 40HP (30KW )  Net weight: kg 9100 9400 10300 11100			0.001 (in	diameter)	
Main drive motor AC motor 40HP (30KW ) Net weight: kg 9100 9400 10300 11100					
Net weight: kg 9100 9400 10300 11100					-
9100 9400 10300 11100 (20065.5) (20727) (22711.5) (24475.5)	Net weight: kg		- X- X-		The state of the s
(20065.5) (20727) (22711.5) (24475.5)		9100	9400	10300	11100
		(20065.5)	(20727)	(22711.5)	(24475.5)





## **MACHINE PHOTOS**











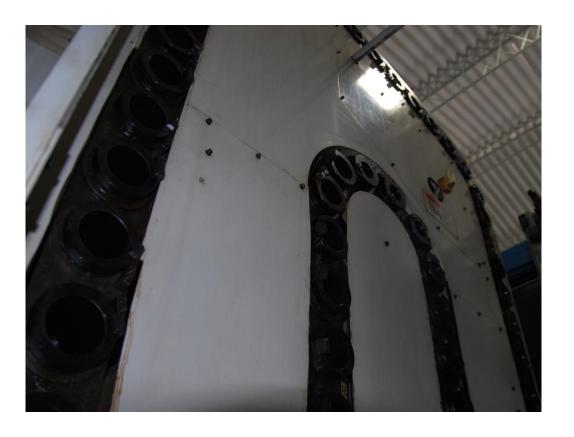




#### (DEALING WITH USED IMPORTED MACHINE)









(DEALING WITH USED IMPORTED MACHINE)





